

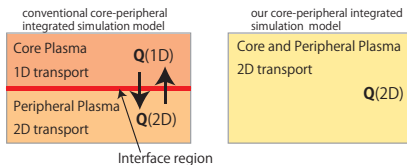
Simulation of two-dimensional transport in tokamak plasmas

Haruki SETO, Atsushi FUKUYAMA

Department of Nuclear Engineering, Kyoto University

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Background and motivation



- **Conventional transport simulation of tokamak plasmas**
 - In the core of a tokamak plasma transport phenomena have been usually described as **one-dimensional problems**.
 - In the peripheral SOL-divertor plasma, transport phenomena are described as **two-dimensional problems**

Recent remarkable progress in computational technology has made more consistent two-dimensional transport simulation of tokamak plasmas feasible.

To carry out two-dimensional transport analysis

- Transport model including poloidal-angle dependence is required.

By employing 2D transport model over the entire plasma

- Analysis of the poloidal angle dependence of the heating efficiency will become available.
- Analysis of the poloidal-angle-dependent transient phenomena will become available.

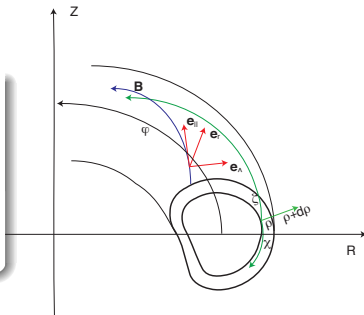
We formulate an axisymmetric two-dimensional transport modeling which analyzes time evolution of plasmas over the entire tokamak.

Coordinates

Magnetic Flux Coordinates System (MFCS):

$$(\xi_1^M, \xi_2^M, \xi_3^M) = (\rho, \chi, \zeta)$$

Suitable description of MHD equilibrium configuration



Local Orthogonal Coordinate System (LOCS):

$$(\xi_1^L, \xi_2^L, \xi_3^L) = (r, \wedge, \parallel)$$

Simpler description on the behavior of magnetized plasmas

Neoclassical Transport Coordinate System (NTCS):

$$(\xi_1^N, \xi_2^N, \xi_3^N) = (\rho, \parallel, \zeta)$$

Good compatibility with neoclassical theory

Assumptions

- Toroidally axisymmetric plasmas
 - Quantities are independent of the toroidal angle variable
- Quantities related to MHD equilibrium depend only on the flux label
- Relaxation processes much slower than Alfvén time scale
- Weak time dependence of basis vectors
 - Time derivatives of basis vectors are small enough to be ignored
- Force balance in MHD time scale
 - Force balance in the radial direction is attained in the MHD time scale

Equations to be derived

Transport equations

- Equation for particle density: $n_e(\rho, \chi)$, $n_i(\rho, \chi)$
- Equation for momentum: $n_e \mathbf{u}_e(\rho, \chi)$, $n_i \mathbf{u}_i(\rho, \chi)$
- Equation for energy transport: $p_e(\rho, \chi)$, $p_i(\rho, \chi)$

Electromagnetic equations

- Poisson equation for electrostatic potential: $\phi(\rho)$
- Magnetic diffusion equation: $t(\rho)$
- Grad-Shafranov equation: $\psi(R, Z)$

Braginskii's equations

Two-fluid transport equation for cold plasma.

- Equation of continuity

$$\frac{\partial n_a}{\partial t} + \nabla \cdot (n_a \mathbf{u}_a) = S_a$$

- Equation of motion

$$\begin{aligned} \frac{\partial}{\partial t} (m_a n_a \mathbf{u}_a) = & -\nabla \cdot (m_a n_a \mathbf{u}_a \mathbf{u}_a) - \nabla p_a - \nabla \cdot \overleftrightarrow{\pi}_a \\ & + e_a n_a (\mathbf{E} + \mathbf{u}_a \times \mathbf{B}) + \mathbf{R}_a + m_a S_{u_a} \mathbf{u}_a \end{aligned}$$

- Equation for energy

$$\frac{3}{2} \frac{\partial p_a}{\partial t} + \nabla \cdot \left(\mathbf{q}_a + \frac{5}{2} p_a \mathbf{u}_a \right) = -\overleftrightarrow{\pi}_a : \nabla \mathbf{u}_a + \mathbf{u}_a \cdot \nabla p_a + Q_a + S_{p_a}$$

Formulation of transport equations

- Policy for the derivation of transport equations
 - For compatibility with the neoclassical transport theory, three components of vector quantities are represented by NTCS.
 - Spatial independent variables are expressed in MFCS
- Neoclassical viscosity tensor in LOCS

$$\overleftrightarrow{\pi}_a \equiv 3 \frac{\mathbf{u}_a \cdot \nabla \chi}{\mathbf{B} \cdot \nabla \chi} \nabla_{\parallel} B \left(\frac{1}{3} \sum_{i=1}^3 \mathbf{e}_{\xi_i^L} \mathbf{e}_{\xi_i^L} - \mathbf{e}_{\parallel} \mathbf{e}_{\parallel} \right)$$

- The equation for particle density

$$\frac{\partial n_a}{\partial t} + \sum_{i=1}^3 \sum_{j=1}^3 \frac{1}{\sqrt{g}} \frac{\partial}{\partial \xi_i^M} (\sqrt{g} n_a \mathcal{T}_{ij}^{MN} u_a^{\xi_j^N}) = S_a$$

where \mathcal{T}_{ij}^{MN} is the transformation matrix from MFCS to NTCS.

- Equation for momentum

$$\begin{aligned} \frac{\partial}{\partial t} (m_a n_a \mathbf{u}_a) = & - \sum_{i=1}^3 F_a^{\text{kin},i} e_{\xi_i^M} - \nabla p_a \\ & - \frac{1}{3} \nabla N_a^{\text{neo}} + \nabla_{\parallel} N_a^{\text{neo}} - N_a^{\text{neo}} \nabla_{\parallel} \ln B + N_a^{\text{neo}} \boldsymbol{\kappa} \\ & + e_a n_a (\mathbf{E} + \mathbf{u}_a \times \mathbf{B}) + \mathbf{R}_a + m_a S_{u_a} \mathbf{u}_a \end{aligned}$$

where, $F_a^{\text{kin},i}$ is the contravariant component of kinetic force in MFCS and N_a^{neo} the parallel coefficient of neoclassical viscosity.

The equation for momentum in each direction of NTCS is derived by taking the scalar product with $e_{\xi_i^N}$.

$$e_{\xi_1^N} \equiv \nabla \rho, \quad e_{\xi_2^N} \equiv e_{\parallel}, \quad e_{\xi_3^N} \equiv \nabla \zeta$$

- Equation for momentum in radial direction

$$0 = -F_a^{\text{kin},1} - \sum_{i=1}^3 g^{1i} \frac{\partial p_a}{\partial \xi_i^{\text{M}}} - \sum_{i=1}^3 \frac{1}{3} g^{1i} \frac{\partial N_a^{\text{neo}}}{\partial \xi_i^{\text{M}}} + N_a^{\text{neo}} \kappa^\rho$$

$$- g^{11} e_a n_a \frac{\partial \phi}{\partial \rho} + e_a n_a \hat{E}^\rho + \sum_{i=1}^3 C_a^{\text{Lor},i} n_a u_a^{\xi_i^{\text{N}}} + R_a^\rho + m_a S_a u_{u_a}^\rho$$

where $C_a^{\text{Lor},i}$ and R_a^ρ are the coefficient of the Lorentz force term and the contravariant radial friction force

$$C_a^{\text{Lor},1} = 0, \quad C_a^{\text{Lor},2} = \frac{e_a B I}{\psi'}, \quad C_a^{\text{Lor},3} = -\frac{e_a B^2 R^2}{\psi'}$$

$$R_a^\rho \equiv \mp \frac{m_e n_e}{\tau_e} u^\rho \mp \frac{3}{2\tau_e \Omega_e} \frac{I}{\sqrt{g} B} n_e \frac{\partial T_e}{\partial \chi}$$

- Equation for momentum in parallel direction

$$\begin{aligned} \frac{\partial}{\partial t} (m_a n_a u_{a\parallel}) = & - \sum_{i=1}^3 C_a^{\text{kin},i} F_a^{\text{kin},i} - \frac{\psi'}{\sqrt{g}B} \frac{\partial p_a}{\partial \chi} \\ & - \frac{\psi'}{\sqrt{g}B} N_a^{\text{neo}} \frac{\partial \ln B}{\partial \chi} + \frac{2}{3} \frac{\psi'}{\sqrt{g}B} \frac{\partial N_a^{\text{neo}}}{\partial \chi} \\ & + e_a n_a \hat{E}_{\parallel} + R_{a\parallel} + m_a S_{u_a} u_{a\parallel} \end{aligned}$$

where $C_a^{\text{kin},i}$ and $R_{a\parallel}$ are the coefficient of kinetic stress force in each direction and the parallel friction force

$$\begin{aligned} C_a^{\text{kin},1} &= \frac{\psi' g_{21}}{\sqrt{g}B}, & C_a^{\text{kin},2} &= \frac{\psi' g_{22}}{\sqrt{g}B}, & C_a^{\text{kin},3} &= \frac{I}{B} \\ R_{a\parallel} &\equiv \mp \left\{ 0.51 \frac{m_e n_e}{\tau_e} (u_{e\parallel} - u_{i\parallel}) + 0.71 \frac{\psi'}{\sqrt{g}B} n_e \frac{\partial T_e}{\partial \chi} \right\} \end{aligned}$$

- Equation for momentum in toroidal direction

$$\begin{aligned} \frac{\partial}{\partial t} (m_a n_a u_a^\zeta) = & - F_a^{\text{kin},3} \\ & - \frac{I\psi'}{\sqrt{g}B^2R^2} N_a^{\text{neo}} \frac{\partial \ln B}{\partial \chi} + \frac{I\psi'}{\sqrt{g}B^2R^2} \frac{\partial N_a^{\text{neo}}}{\partial \chi} + N_a^{\text{neo}} \kappa^\zeta \\ & + e_a n_a \hat{E}^\zeta + \frac{e_a \psi'}{R^2} n_a u_a^\rho + R_a^\zeta + m_a S_{u_a} u_a^\zeta \end{aligned}$$

where R_a^ζ is the contravariant toroidal friction force

$$\begin{aligned} R_a^\zeta \equiv & \mp \frac{m_e n_e}{\tau_e} \left\{ (u_e^\zeta - u_i^\zeta) - 0.49 \frac{I}{BR^2} (u_{e\parallel} - u_{i\parallel}) \right\} \\ & \mp 0.71 \frac{\psi' I}{\sqrt{g}B^2R^2} n_e \frac{\partial T_e}{\partial \chi} \mp \sum_{i=1}^3 \frac{3}{2\tau_e \Omega_e} \frac{\psi' g^{1i}}{BR^2} n_e \frac{\partial T_e}{\partial \xi_i^\zeta} \end{aligned}$$

Equation for internal energy is obtained by transforming equation for energy transport of Braginskii's equation into the advection-diffusion form

- Equation for internal energy

$$\frac{\partial}{\partial t} \left(\frac{3}{2} p_a \right) + \nabla \cdot \left(p_a \mathbf{u}_{p_a} - n_a \overleftrightarrow{\chi}_a \cdot \nabla T_a \right) = Q_{p_a}$$

where $\mathbf{u}_{p_a} \equiv (5/2)\mathbf{u}_a + p_a^{-1}\mathbf{q}_{u_a}$, Q_{p_a} and $\overleftrightarrow{\chi}_a$ are the the energy flow velocity, the energy source term and the diffusion coefficient tensor and respectively.

Current program design

Variables for TASK/T2:

$$n_a, p_a, n_a u_a^\rho, n_a u_{a\parallel}, n_a u_s^\zeta$$

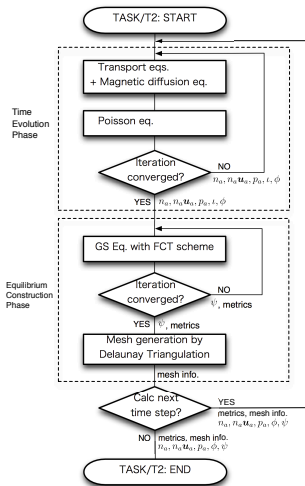
$$\phi(\rho), t(\rho), \psi(R, Z)$$

Metrics

$$g_{ij}, g^{ij}, \sqrt{g}$$

Mesh info.

Boundary Condition,
Element-Node Relation,
Node-Node Connectivity, etc...



Brief flowchart of TASK/T2
(under development)

Current status and issues of TASK/T2: TE-phase

Employed algorithms

- Discretization:
 - SUPG-FEM: Transport eqs.
 - BG-FEM: Magnetic diffusion eq. and Poisson eq.
- Element: Multi-scale rectangular element
- Matrix Solver: Krylov subspace iterative method (PETSc library)
- Nonlinear Solver: Picard iteration

We have derived transport eqs. and been coding TE-Phase; however, there are still remains some issues in transport modeling.

- Appropriate modeling of gyro-viscous force in core region
- Appropriate energy cancellation between diamagnetic terms

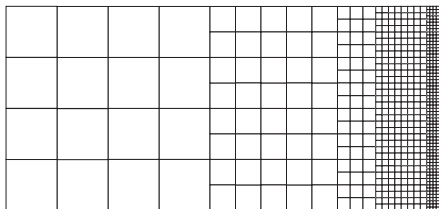
Current status and issues of TASK/T2: EC-phase

Grad-Shafranov Eq. with FCT scheme

- TASK/EQU
 - Free boundary 2D MHD equilibrium solver with FCT scheme included in integrated toroidal plasma modeling code TASK.

Mesh generation

- Multi-scale structural rectangular mesh generation algorithm



Basic concept of multi-scale structural rectangular mesh

Summary and Future works

Summary

- A set of equations required for two-dimensional transport modeling for tokamak plasmas has been derived for integrated analysis of core and peripheral plasmas
 - Transport equations are derived from Braginskii's equations with the neoclassical viscosity in MFCS and reduced to two-dimensional with toroidal axisymmetry.
 - By combining these transport equations with the electromagnetic equations, a more self-consistent two-dimensional transport analysis including the field evolution will be available.

Future works

- Developing the two-dimensional transport code using the FEM to simulate time evolution of tokamak plasmas.
 - Analysis of the asymmetric effect in limiter configuration
 - Full 2D transport analysis in entire tokamak plasma